

# Independence (Linear and Affine)

### Linear Algebra

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# Introduction





## Linear Equation





#### Size of the House



- □ #Room
- □ Size
- □ #Bedroom
- □ Age
- $\hfill\square$  Address features: Street, Alley,  $\cdots$
- □ Size of part1, part2, part3, part4
- □ Floors
- □ #Bathrooms
- **D** ····





#### Size of the House

## Least Squares Error Correction





## Least Squares















# Linear Algebra and Machine Learning Application









#### Simple regression



y = y-intercept + slope x

#### **Multiple regression**



y = y-intercept + slope x + slope z

# Linear Independence

# Linear Independence (Algebra)



#### Definition

#### Dependent

- $\label{eq:constraint} \Box \quad \text{For at least one } \lambda \neq 0 \qquad \qquad 0 = \lambda_1 v_1 + \lambda_2 v_2 + \dots + \lambda_n v_n, \qquad \lambda \in \mathbb{R}$
- □ A set of vectors is dependent if at least one vector in the set can be expressed as a linear weighted combination of the other vectors in that set.

# Definition Independent $\Box$ Only when all $\lambda_i = 0$ $0 = \lambda_1 v_1 + \lambda_2 v_2 + \dots + \lambda_n v_n$ , $\lambda \in \mathbb{R}$ $\Box$ No vector in the set is a linear combination of the others (has only the trivial solution)

# Linear Independence (Geometry)



#### Definition

A set of vectors is linear independent if the subspace dimensionality (its span) equals the number of vectors.

#### Example

□ vectors spans?





### Example

$$\square \quad \text{Let } v_1 = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}, v_2 = \begin{bmatrix} 4 \\ 5 \\ 6 \end{bmatrix}, and v_3 = \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix}.$$

**a**) 
$$v_1 = \begin{bmatrix} 3 \\ 1 \end{bmatrix}, v_2 = \begin{bmatrix} 6 \\ 2 \end{bmatrix}$$
 **b**)  $v_1 = \begin{bmatrix} 3 \\ 2 \end{bmatrix}, v_2 = \begin{bmatrix} 6 \\ 2 \end{bmatrix}$ 



## Theorem

Any set of vectors that contains the zeros vector is guaranteed to be linearly dependent.

### Proof



#### Theorem

An indexed set  $S = \{v_1, ..., v_n\}$  of two or more vectors is linearly dependent if and only if at least one of the vectors in S is a linear combination of the others. In fact, if S is linearly dependent and  $v_1 \neq 0$ , then some  $v_j$  (with j > 1) is a linear combination of the preceding vectors,  $v_1, ..., v_{j-1}$ .

### Proof

Does not say that every vector

Does not say that every vector in a linearly dependent set is a linear combination of the preceding vectors. A vector in a linearly dependent set may fail to be a linear combination of the other vectors.

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## Proof

If some  $v_j$  in *S* equals a linear combination of the other vectors, then  $v_j$  can be subtracted from both sides of the equation, Producing a linear dependence relation with a nonzero weight (-1) on  $v_j$ . [For instance, if  $v_1 = c_2v_2 + c_3v_3$ , then  $0 = (-1)v_1 + c_2v_2 + c_3v_3 + 0v_4 + \cdots + 0v_n$ .] Thus *S* is linearly dependent.

Conversely, suppose *S* is linearly dependent. If  $v_1$  is zero, then it is a (trivial) linear combination of the other vectors in *S*. Otherwise,  $v_1 \neq 0$ , and there exist weights  $c_1, ..., c_n$  not all zero, such that

$$c_1 v_1 + c_2 v_2 + \dots + c_p v_n = 0$$



## Proof

Let *j* be the largest subscript for which  $c_j \neq 0$ . If j = 1, then  $c_1v_1 = 0$ , which is impossible because  $v_1 \neq 0$ . So j > 1 and

$$c_{1}v_{1} + \dots + c_{j}v_{j} + 0v_{j+1} + 0v_{n} = 0$$

$$c_{j}v_{j} = -c_{1}v_{1} - \dots - c_{j-1}v_{j-1}$$

$$v_{j} = \left(-\frac{c_{1}}{c_{j}}\right)v_{1} + \dots + \left(-\frac{c_{j-1}}{c_{j}}\right)v_{j-1}$$



The vectors coming from the vector form of the solution of a matrix equation Ax = 0 are linearly independent

### Example

 $\Box$  Vectors related to  $x_2$  and  $x_3$  are linear independent.

 $\Box$  Columns of A related to to  $x_2$  and  $x_3$  are linear dependent.

$$\Box \operatorname{Span}\{A_1, A_2, A_3\} = \operatorname{Span}\{A_1\}$$
$$A = \begin{bmatrix} 1 & -1 & 2 \\ -2 & 2 & -4 \end{bmatrix} \qquad x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = x_2 \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} -2 \\ 0 \\ 1 \end{bmatrix}$$



## Important

□ If a collection of vectors is linearly dependent, then any superset

of it is linearly dependent.

□ Any nonempty subset of a linearly independent collection of

vectors is linearly independent.



## Theorem

 $\Box$  Any set of p > n vectors in  $\mathbb{R}^n$  is necessarily dependent.

 $\Box$  Any set of  $p \leq n$  vectors in  $\mathbb{R}^n$  could be linearly independent.

Proof

## Example



## Example

 a.
  $\begin{bmatrix} 1\\7\\6 \end{bmatrix}, \begin{bmatrix} 2\\0\\9 \end{bmatrix}, \begin{bmatrix} 3\\1\\5 \end{bmatrix}, \begin{bmatrix} 4\\1\\8 \end{bmatrix}$  

 b.
  $\begin{bmatrix} 2\\3\\5 \end{bmatrix}, \begin{bmatrix} 0\\0\\0 \end{bmatrix}, \begin{bmatrix} 1\\1\\8 \end{bmatrix}$ 

$$c. \begin{bmatrix} -2\\ 4\\ 6\\ 10 \end{bmatrix}, \begin{bmatrix} 3\\ -6\\ -9\\ 15 \end{bmatrix}$$



 $\Box$  Suppose vectors  $v_1, \dots, v_n$  are linearly dependent:

$$c_1v_1 + c_2v_2 + \dots + c_nv_n = 0$$

with  $c_1 \neq 0$ . Then:

$$span\{v_1, \dots, v_n\} = span\{v_2, \dots, v_n\}$$

When we write a vector space as the space of a list of vectors, we would like that list to be as short as possible. This can achieved by iterating.



### Theorem

## Suppose x is linear combination of linearly independent vectors

 $v_1, \ldots, v_n$ :

$$x = \beta_1 v_1 + \dots + \beta_n v_n$$

The coefficients 
$$\beta_1$$
, ...,  $\beta_n$  are unique.

### Proof



### Important

- □ Step 1: Count the number of vectors (call that number p) in the set and compare to n in  $\mathbb{R}^n$ . As mentioned earlier, if p > n, then the set is necessarily dependent. If  $p \le n$  then you have to move on to step 2.
- □ Step 2: Check for a vector of all zeros. Any set that contains the zeros vector is a dependent set.
- □ The rank of a matrix is the estimate of the number of linearly independent rows or columns in a matrix.

# **Functions Linearly Independent**

- □ Let f(t) and g(t) be differentiable functions. Then they are called linearly dependent if there are nonzero constants  $c_1$  and  $c_2$  with  $c_1f(t) + c_2g(t) = 0$

for all t. Otherwise they are called linearly independent.

Example

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Linearly dependent or independent?

□Functions f(t) = 2 \sin^2 t and g(t) = 1 - \cos^2 t

□Functions \{\sin^2 x, \cos^2 x, \cos(2x)\} \subset \mathcal{F}
```

# **Polynomials Linearly Independent**



#### Example

# Are (1 - x), (1 + x), $x^2$ linearly independent?

# Affine Combination



• For vectors  $x_1, x_2, ..., x_k$ : any point y is a linear combination of them iff:

$$y = \alpha_1 x_1 + \alpha_2 x_2 + \dots + \alpha_i x_i \quad \forall i, \alpha_i \in \mathbb{R}$$

□ Instead of being positive, if we put the restriction that  $\alpha_i$ 's sum up to 1, it is called an **affine combination**  $y = \alpha_1 x_1 + \alpha_2 x_2 + \dots + \alpha_i x_i$   $\forall i, \alpha_i \in \mathbb{R}, \sum_i \alpha_i = 1$ 



- □ Linear combination and Affine combination (no origin, independent of the concepts of distance and measure of angles, keeping only the properties related to parallelism and ratio of lengths for parallel line segments)
- Affine combination of two vectors
- □ Affine combination of z





#### Theorem

A point y in  $\mathbb{R}^n$  is an affine combination of  $v_1, \ldots, v_p$  in  $\mathbb{R}^n$  if and only if  $y - v_i$  is a linear combination of the translated points  $v_1 - v_i, v_2 - v_i, \ldots, v_p - v_i$ Proof?

#### Example

Find a vector equation and parametric equations of the plane in  $\mathbb{R}^4$  that passes through (-17, 6, 29, 0), (-13, 3, 25, -2) and (-15, 6, 25, -1).

# Affine Independence

## Definition



An indexed set of points  $\{v_1, ..., v_k\}$  in  $\mathbb{R}^n$  is **affinely dependent** if there exists

real numbers  $c_1, \ldots, c_k$ , not all zero, such that

 $c_1 + \dots + c_k = 0$  and  $c_1 v_1 + \dots + c_k v_k = 0$ 

Otherwise, the set is **affinely independent**.



- How to find affine dependent from linear dependent definition and affine combination
- □ Uniqueness of affine combination of affinely independent set.
- □ Linear dependence relation with affine dependence

## Affine Independence

### Note



Given an indexed set  $S = \{v_1, ..., v_p\}$  in  $\mathbb{R}^n$ , with  $p \ge 2$ , the following statements are logically equivalent. That is, either they are all true statements or they are all false.

- a. S is affinely dependent.
- b. One of the points in S is an affine combination of other points in S.
- c. The set  $\{v_2 v_1, ..., v_p v_1\}$  in  $\mathbb{R}^n$  is linearly dependent.

# $\mathbb{R}^n$ contains at most n + 1 affinely independent points

## Example



## Example

Let 
$$v_1 = \begin{bmatrix} 1 \\ 3 \\ 7 \end{bmatrix}$$
,  $v_2 = \begin{bmatrix} 2 \\ 7 \\ 6.5 \end{bmatrix}$ ,  $v_3 = \begin{bmatrix} 0 \\ 4 \\ 7 \end{bmatrix}$ , and  $v_4 = \begin{bmatrix} 0 \\ 14 \\ 6 \end{bmatrix}$ , and let  $S = \{v_1, \dots, v_4\}$ . Is  $S$ 

affinely dependent?







Span	Linearly Independent
Want many vectors in small space	Want few vectors in big space
Adding vectors to list only helps	Deleting vectors from list only helps
Suppose that $v_1, \dots, v_k$ are columns of A, now we have: AX= b has solution $\Leftrightarrow b \in span\{v_1, \dots, v_k\}$	Suppose that $v_1,, v_k$ are columns of A, now we have: AX = 0 has only trivial solution(X=0) $\Leftrightarrow v_1,, v_k$ are linearly independent.



Description Page 97 LINEAR ALGEBRA: Theory, Intuition, Code

□ Page 213: David Cherney,

□ Page 54: Linear Algebra and Optimization for Machine Learning